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Robotis Arm, OpenCM 9.08 & Dynamixel XM430

Learn how to program and control a Robotis Arm powered by a OpenCM 9.04 board and Dynamixel servos using Synthiam software platform.

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Step 1

In this Tutorial we will be connecting to an OpenCM 9.04 board to control a Robotis Arm moved by Dynamixel XM430 Servos in Synthiam Platform. We will go over firmware installations and using Skills like Auto Positioning and Speech Recognition.
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